

New representations of focal curves in the special ϕ -Ricci Symmetric Para-Sasakian Manifold \mathbb{P}

Talat Körpınar and Essin Turhan

Abstract

In this paper, we study matrix representations of focal curves in terms of biharmonic curves in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold \mathbb{P} . We construct new parametric equations of focal curves in terms of matrix representations in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold \mathbb{P} .

key words. Focal curve, Biharmonic curve, Matrices, Para-Sasakian manifold.

1 Introduction

A smooth map $\phi : N \longrightarrow M$ is said to be biharmonic if it is a critical point of the bienergy functional:

$$E_2(\phi) = \int_N \frac{1}{2} |\mathcal{T}(\phi)|^2 dv_h,$$

where $\mathcal{T}(\phi) := \text{tr} \nabla^\phi d\phi$ is the tension field of ϕ

The Euler-Lagrange equation of the bienergy is given by $\mathcal{T}_2(\phi) = 0$. Here the section $\mathcal{T}_2(\phi)$ is defined by

$$\mathcal{T}_2(\phi) = -\Delta_\phi \mathcal{T}(\phi) + \text{tr} R(\mathcal{T}(\phi), d\phi) d\phi, \quad (1.1)$$

and called the bitension field of ϕ . Non-harmonic biharmonic maps are called proper biharmonic maps.

In this paper, we study matrix representations of focal curves in terms of biharmonic curves in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold \mathbb{P} . We construct new parametric equations of focal curves in terms of matrix representations in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold \mathbb{P} .

2 Special Three-Dimensional ϕ -Ricci Symmetric Para-Sasakian Manifold \mathbb{P}

An n -dimensional differentiable manifold M is said to admit an almost para-contact Riemannian structure (ϕ, ξ, η, g) , where ϕ is a $(1, 1)$ tensor field, ξ is a vector field, η is a 1-form and g is a Riemannian metric on M such that

$$\phi\xi = 0, \quad \eta(\xi) = 1, \quad g(X, \xi) = \eta(X), \quad (2.1)$$

$$\phi^2(X) = X - \eta(X)\xi, \quad (2.2)$$

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \quad (2.3)$$

for any vector fields X, Y on M , [2].

Definition 2.1. A para-Sasakian manifold M is said to be locally ϕ -symmetric if

$$\phi^2((\nabla_W R)(X, Y)Z) = 0,$$

for all vector fields X, Y, Z, W orthogonal to ξ [2].

Definition 2.2. A para-Sasakian manifold M is said to be ϕ -symmetric if

$$\phi^2((\nabla_W R)(X, Y)Z) = 0,$$

for all vector fields X, Y, Z, W on M .

Definition 2.3. A para-Sasakian manifold M is said to be ϕ -Ricci symmetric if the Ricci operator satisfies

$$\phi^2((\nabla_X Q)(Y)) = 0,$$

for all vector fields X and Y on M and $S(X, Y) = g(QX, Y)$.

If X, Y are orthogonal to ξ , then the manifold is said to be locally ϕ -Ricci symmetric.

We consider the three-dimensional manifold

$$\mathbb{P} = \{(x^1, x^2, x^3) \in \mathbb{R}^3 : (x^1, x^2, x^3) \neq (0, 0, 0)\},$$

where (x^1, x^2, x^3) are the standard coordinates in \mathbb{R}^3 . We choose the vector fields

$$\mathbf{e}_1 = e^{x^1} \frac{\partial}{\partial x^2}, \quad \mathbf{e}_2 = e^{x^1} \left(\frac{\partial}{\partial x^2} - \frac{\partial}{\partial x^3} \right), \quad \mathbf{e}_3 = -\frac{\partial}{\partial x^1} \tag{2.4}$$

are linearly independent at each point of \mathbb{P} . Let g be the Riemannian metric defined by

$$\begin{aligned} g(\mathbf{e}_1, \mathbf{e}_1) &= g(\mathbf{e}_2, \mathbf{e}_2) = g(\mathbf{e}_3, \mathbf{e}_3) = 1, \\ g(\mathbf{e}_1, \mathbf{e}_2) &= g(\mathbf{e}_2, \mathbf{e}_3) = g(\mathbf{e}_1, \mathbf{e}_3) = 0. \end{aligned} \tag{2.5}$$

Let η be the 1-form defined by

$$\eta(Z) = g(Z, \mathbf{e}_3) \text{ for any } Z \in \chi(\mathbb{P}).$$

Let ϕ be the (1,1) tensor field defined by

$$\phi(\mathbf{e}_1) = \mathbf{e}_2, \quad \phi(\mathbf{e}_2) = \mathbf{e}_1, \quad \phi(\mathbf{e}_3) = 0. \tag{2.6}$$

Then using the linearity of ϕ and g we have

$$\eta(\mathbf{e}_3) = 1, \tag{2.7}$$

$$\phi^2(Z) = Z - \eta(Z)\mathbf{e}_3, \tag{2.8}$$

$$g(\phi Z, \phi W) = g(Z, W) - \eta(Z)\eta(W), \tag{2.9}$$

for any $Z, W \in \chi(\mathbb{P})$. Thus for $\mathbf{e}_3 = \xi$, (ϕ, ξ, η, g) defines an almost para-contact metric structure on \mathbb{P} .

Let ∇ be the Levi-Civita connection with respect to g . Then, we have

$$[\mathbf{e}_1, \mathbf{e}_2] = 0, \quad [\mathbf{e}_1, \mathbf{e}_3] = \mathbf{e}_1, \quad [\mathbf{e}_2, \mathbf{e}_3] = \mathbf{e}_2.$$

3 Matrix Representation of Focal Curves in the Special Three-Dimensional ϕ -Ricci Symmetric Para-Sasakian Manifold \mathbb{P}

For a unit speed curve γ , the curve consisting of the centers of the osculating spheres of γ is called the parametrized focal curve of γ . The hyperplanes normal to γ at a point consist of the set of centers of all spheres tangent to γ at that point. Hence the center of the osculating spheres at that point lies in such a normal plane. Therefore, denoting the focal curve by C_γ , we can write

$$C_\gamma(s) = (\gamma + c_1\mathbf{N} + c_2\mathbf{B})(s), \quad (3.1)$$

where the coefficients c_1, c_2 are smooth functions of the parameter of the curve γ , called the first and second focal curvatures of γ , respectively. Further, the focal curvatures c_1, c_2 are defined by

$$c_1 = \frac{1}{\kappa}, \quad c_2 = \frac{c_1'}{\tau}, \quad \kappa \neq 0, \quad \tau \neq 0. \quad (3.2)$$

Lemma 3.1. *Let $\gamma : I \rightarrow \mathbb{P}$ be a unit speed biharmonic curve and C_γ its focal curve on \mathbb{P} . Then,*

$$c_1 = \frac{1}{\kappa} = \text{constant and } c_2 = 0. \quad (3.3)$$

Proof. Using (2.3) and (3.2), we get (3.3).

Lemma 3.2. *Let $\gamma : I \rightarrow \mathbb{P}$ be a unit speed biharmonic curve and C_γ its focal curve on \mathbb{P} . Then,*

$$C_\gamma(s) = (\gamma + c_1\mathbf{N})(s). \quad (3.4)$$

Theorem 3.3. *(see [13]) Let $\gamma : I \rightarrow \mathbb{P}$ be a non-geodesic biharmonic curve in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold \mathbb{P} . Then,*

$$\begin{aligned} \mathcal{A}\gamma &= \sqrt{-\text{trace}(\mathcal{A}^2)}(-\cos\varphi, \sin\varphi e^{-s\cos\varphi+C_1}(\sin[\mathbb{k}s+C] + \cos[\mathbb{k}s+C]), \\ &\quad \sin\varphi e^{-s\cos\varphi+C_1}\sin[\mathbb{k}s+C]), \\ \mathcal{A}^2\gamma &= \left(\frac{\sqrt{\text{trace}(\mathcal{A}^4)}}{2}\right)(-\frac{\sin^2\varphi}{2}s^2 + \overline{C}_1s + \overline{C}_2, \\ &\quad e^{-\frac{\sin^2\varphi}{2}s^2 + \overline{C}_1s + \overline{C}_2}(\mathbb{k}\sin\varphi\sin[\mathbb{k}s+C] + \cos\varphi\sin\varphi\cos[\mathbb{k}s+C]) \\ &\quad + e^{-\frac{\sin^2\varphi}{2}s^2 + \overline{C}_1s + \overline{C}_2}(-\mathbb{k}\sin\varphi\cos[\mathbb{k}s+C] + \cos\varphi\sin\varphi\sin[\mathbb{k}s+C]), \\ &\quad -e^{-\frac{\sin^2\varphi}{2}s^2 + \overline{C}_1s + \overline{C}_2}(-\mathbb{k}\sin\varphi\cos[\mathbb{k}s+C] + \cos\varphi\sin\varphi\sin[\mathbb{k}s+C])), \end{aligned} \quad (3.5)$$

where C, \bar{C}_1, \bar{C}_2 are constants of integration and $\mathbb{k} = \frac{\sqrt{\kappa^2 - \sin^2 \varphi}}{\sin \varphi}$.

Now, let us define a special form of focal curve.

Lemma 3.4. *Let $\gamma : I \rightarrow \mathbb{P}$ be a regular curve in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold \mathbb{P} . Then,*

$$C_\gamma(s) = \gamma(s) + c_1 \frac{\mathcal{A}^2 \gamma}{\sqrt{\text{trace}(\mathcal{A}^4)}}. \tag{3.6}$$

Proof. Using Theorem 3.3, we immediately obtain

$$\mathbf{N} = \left(\sqrt{\text{trace}(\mathcal{A}^4)} \right)^{-1} \mathcal{A}^2 \gamma.$$

According to the definition of focal curve we have (3.6).

Theorem 3.5. *(see [13]) Let $\gamma : I \rightarrow \mathbb{P}$ be a non-geodesic biharmonic curve in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold \mathbb{P} . Then the new curvatures of this curve are*

$$\kappa = - \frac{\sqrt{\text{trace}(\mathcal{A}^4)}}{\text{trace}(\mathcal{A}^2)}, \tag{3.7}$$

$$\tau = \Re \left[\frac{-\text{trace}(\mathcal{A}^6)}{\left(\sqrt{-\text{trace}(\mathcal{A}^2)}\right)^4 \sqrt{\text{trace}(\mathcal{A}^4)}} - \frac{\left(\text{trace}(\mathcal{A}^4)\right)^{\frac{3}{4}}}{\left(\sqrt{-\text{trace}(\mathcal{A}^2)}\right)^6} \right],$$

where $\Re = \left[\frac{\text{trace}(\mathcal{A}^6)}{\left(\sqrt{-\text{trace}(\mathcal{A}^2)}\right)^6} - \frac{\left(\text{trace}(\mathcal{A}^4)\right)^2}{\left(\sqrt{-\text{trace}(\mathcal{A}^2)}\right)^5} \right]^{-\frac{1}{2}}$.

Using above Lemma and Theorem we have following result:

Theorem 3.6. *Let $\gamma : I \rightarrow \mathbb{P}$ be a biharmonic curve parametrized by arc length. If C_γ is a focal curve of γ , then the parametric equations of C_γ are*

$$\begin{aligned}
\tilde{x}^1(s) &= -\frac{(\text{trace}(\mathcal{A}^2))^2}{\text{trace}(\mathcal{A}^4)}\left(-\frac{\sin^2\varphi}{2}s^2 + \overline{C}_1s + \overline{C}_2\right) - \cos\varphi s + C_1, \\
\tilde{x}^2(s) &= -\frac{(\text{trace}(\mathcal{A}^2))^2\sin^3\varphi}{\text{trace}(\mathcal{A}^4) - (\text{trace}(\mathcal{A}^2))^2\sin^4\varphi}e^{-s\cos\varphi + C_1}(\Pi\cos[\Pi s + C] + [-\Pi + \cos\varphi]\sin[\Pi s + C]) \\
&\quad -\frac{(\text{trace}(\mathcal{A}^2))^2}{\text{trace}(\mathcal{A}^4)}e^{-\frac{\sin^2\varphi}{2}s^2 + \overline{C}_1s + \overline{C}_2}(\Pi\sin\varphi\sin[\Pi s + C] + \cos\varphi\sin\varphi\cos[\Pi s + C]) \\
&\quad -\frac{(\text{trace}(\mathcal{A}^2))^2}{\text{trace}(\mathcal{A}^4)}e^{-\frac{\sin^2\varphi}{2}s^2 + \overline{C}_1s + \overline{C}_2}(-\Pi\sin\varphi\cos[\Pi s + C] + \cos\varphi\sin\varphi\sin[\Pi s + C]) + C_2, \\
\tilde{x}^3(s) &= -\frac{(\text{trace}(\mathcal{A}^2))^2\sin^3\varphi}{\text{trace}(\mathcal{A}^4) - (\text{trace}(\mathcal{A}^2))^2\sin^4\varphi}e^{-s\cos\varphi + C_1}(-\cos\varphi\cos[\Pi s + C] + [\Pi s + C]\sin[\Pi s + C]) \\
&\quad +\frac{(\text{trace}(\mathcal{A}^2))^2}{\text{trace}(\mathcal{A}^4)}e^{-\frac{\sin^2\varphi}{2}s^2 + \overline{C}_1s + \overline{C}_2}(-\Pi\sin\varphi\cos[\Pi s + C] + \cos\varphi\sin\varphi\sin[\Pi s + C]) + C_3,
\end{aligned} \tag{3.8}$$

where $C, \overline{C}_1, \overline{C}_2, C_1, C_2, C_3$ are constants of integration and $\Pi = \left[\frac{\sqrt{\text{trace}(\mathcal{A}^4) - (\text{trace}(\mathcal{A}^2))^2\sin^2\varphi}}{(\text{trace}(\mathcal{A}^2))\sin\varphi} \right]$.

Proof. Assume that γ be a spacelike biharmonic curve and C_γ its focal curve on \mathbb{P} . Substituting equation (3.5) into Lemma 3.4, and by using the Mathematica program we have above system. This completes the proof of the theorem.

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Talat Körpınar¹, Essin Turhan
Firat University, Department of Mathematics
23119, Elazığ, TURKEY
e-mail: talatkorpınar@gmail.com, essin.turhan@gmail.com